

UNIVERSAL CONVEYOR SYSTEM

¹Mr. Inde L. J., ²Mr. Aurad S. S., ³Mr. Umarani S. B., ⁴Mr. Sangundi H. S., ⁵Mr. Ghurghure K. A
Students, Department of Mechanical Engineering, SVSMD's KKI Polytechnic, Akkalkot, Maharashtra,
India.^{1,2,3,4}

Lecturer, Department of Mechanical Engineering, SVSMD's KKI Polytechnic, Akkalkot, Maharashtra, India.⁵
svsmdmechdept@gmail.com

ABSTRACT

Material handling is an essential operation in manufacturing industries, warehouses, packaging units, and assembly lines. Conventional conveyor systems transport materials in a single fixed direction and often require multiple conveyors to achieve multi-directional movement. This increases installation cost, space requirements, power consumption, and maintenance expenses.

The Universal Conveyor System is designed as a flexible and economical solution for multi-directional material handling using a single conveyor unit. The system consists of a conveyor belt mounted on a rotating and adjustable frame supported by a vertical stand. A gear-driven DC motor drives the conveyor belt, while an additional motor provides inclination adjustment for transferring materials at different heights.

The proposed system reduces manual handling, improves productivity, minimizes worker fatigue, and optimizes floor space utilization. The conveyor is compact, portable, cost-effective, and easy to fabricate using commonly available materials. Due to its versatility and simplicity, the Universal Conveyor System is suitable for industrial applications, warehouses, educational demonstrations, and small-scale manufacturing units.

INTRODUCTION

Material handling plays a vital role in industrial production systems. Efficient movement of materials between different processing stations directly affects productivity, operational cost, and workplace safety. Conveyor systems are among the most widely used material handling equipment because they provide continuous transportation of materials with minimal human effort.

Traditional belt conveyors are designed to transfer materials in only one direction. In many industrial situations, materials must be delivered to different locations and at different heights. Achieving such movement typically requires multiple conveyor systems, resulting in increased installation costs, larger space requirements, and higher maintenance expenses.

To overcome these limitations, a Universal Conveyor System has been developed. The system integrates a conventional belt conveyor with a rotating base and adjustable inclination mechanism. This arrangement allows material transfer in multiple directions and at varying heights using a single conveyor unit. The design improves flexibility while reducing operational complexity and overall cost.

LITERATURE SURVEY

Conveyor systems are widely used in manufacturing industries, warehouses, and assembly lines due to their efficiency in transporting materials. Belt conveyors are particularly popular because of their simple construction, low maintenance requirements, and reliable performance.

Various studies have been conducted on inclined conveyor systems used for transferring materials between different elevations. While such conveyors are effective for vertical movement, they still operate in a fixed direction and require additional systems for multi-directional transfer.

Researchers have also developed rotating conveyor systems capable of directing materials to multiple locations. However, these systems are often complex, expensive, and unsuitable for small-scale industries or educational applications.

The review of existing systems indicates a need for a compact, economical, and versatile conveyor capable of transferring materials in different directions while occupying minimal space. The Universal Conveyor System addresses this requirement by combining belt conveyor technology with rotational and inclination adjustment mechanisms.

CONSTRUCTION AND WORKING

The Universal Conveyor System consists of several mechanical and electrical components assembled to achieve flexible material transfer.

1. Base Platform

The base platform supports the entire conveyor assembly. It is fabricated using a wooden board and equipped with wheels for portability.

2. Vertical Support Stand

A mild steel support stand is mounted on the base platform. It provides structural stability and serves as the pivot point for conveyor inclination adjustment.

3. Conveyor Frame

The conveyor frame consists of two side plates connected using fasteners. It supports rollers, shafts, and the conveyor belt.

4. Conveyor Belt

A rubber or fabric belt is mounted over rollers and acts as the primary medium for transporting materials.

5. Rollers

Drive and idle rollers support the belt and facilitate smooth movement during operation.

6. Gear Mechanism

A spur gear arrangement transfers power from the motor shaft to the conveyor shaft. The gear system increases torque and ensures efficient power transmission.

7. Drive Motor

A 12 V DC geared motor drives the conveyor belt and provides continuous material transportation.

8. Inclination Motor

A separate DC motor controls conveyor inclination, allowing the belt to operate at different angles.

9. Shaft

Steel shafts support rollers and gears while transmitting rotational motion.

10. Wheels

Four wheels mounted beneath the base provide mobility and facilitate movement of the conveyor system.

Working Principle

The Universal Conveyor System operates on the principle of belt conveyor material transportation combined with adjustable inclination and directional flexibility.

Step-by-Step Working

1. The conveyor is positioned at the desired location.
2. The required inclination angle is adjusted using the inclination motor.

3. Power is supplied to the drive motor.
4. The motor rotates the pinion gear.
5. The pinion gear drives the larger spur gear mounted on the conveyor shaft.
6. The conveyor shaft rotates the drive roller.
7. The conveyor belt begins continuous movement over the rollers.
8. Materials placed at the loading end are transported toward the unloading end.
9. Inclination adjustment allows transfer at different elevations.
10. The system can be repositioned easily due to its mobile base.

Working Mechanism

Electrical Power → Drive Motor → Gear Transmission → Conveyor Shaft Rotation → Belt Movement → Material Transfer

Inclination Motor → Conveyor Frame Adjustment → Variable Height Material Handling

The combination of conveyor motion and adjustable inclination provides efficient multi-directional material transportation.

CONCLUSION

The Universal Conveyor System successfully demonstrates an economical and flexible approach to material handling. By integrating belt conveyor technology with inclination adjustment and mobility features, the system enables efficient transportation of materials using a single conveyor unit.

The developed model reduces manual handling effort, improves productivity, minimizes operational costs, and saves floor space. Its simple construction and low fabrication cost make it suitable for small-scale industries, warehouses, packaging units, and educational institutions.

The successful testing of the prototype confirms its ability to transport materials smoothly while providing flexibility in direction and height adjustment. The project demonstrates the practical application of conveyor technology for modern material handling requirements.

FUTURE SCOPE

The Universal Conveyor System can be further improved through advanced technologies and automation features.

1. Integration of PLC-based automation for intelligent control.
2. Addition of sensor-based material detection systems.
3. Implementation of variable speed drive mechanisms.
4. Development of automatic rotational positioning systems.
5. Remote monitoring using IoT technology.
6. Incorporation of robotic loading and unloading mechanisms.
7. Increased load-carrying capacity for industrial applications.
8. Development of fully automated warehouse material handling systems.
9. Integration with Industry 4.0 manufacturing environments.
10. Enhancement of safety and energy efficiency through smart control systems.

These improvements can significantly enhance system performance and expand its industrial applications in the future.

REFERENCES

1. **R. S. Khurmi & J. K. Gupta** – *Theory of Machines*
 2. **R. S. Khurmi & J. K. Gupta** – *A Textbook of Machine Design*
 3. **V. B. Bhandari** – *Design of Machine Elements*
 4. **S. K. Hajra Choudhury** – *Elements of Workshop Technology*
 5. **CEMA (Conveyor Equipment Manufacturers Association)** – *Belt Conveyors for Bulk Materials*
1. Khurmi, R.S. and Gupta, J.K., *A Textbook of Machine Design*, S. Chand Publications.
 2. Bhandari, V.B., *Design of Machine Elements*, McGraw Hill Education.
 3. Hajra Choudhury, S.K., *Elements of Workshop Technology*, Media Promoters & Publishers.
 4. Conveyor Equipment Manufacturers Association (CEMA), *Belt Conveyors for Bulk Materials*.
 5. CEMA. Available at: www.cemanet.org
 6. Dorner Conveyors. Available at: www.dornerconveyors.com

